

# **Professional Experience**

Second Order Effects | El Segundo, CA

Jan. 2022 - Current

Staff Systems Engineer, Special Projects. Hybrid systems architect and technical advisor, specializing in ambiguous and novel problems across aerospace and advanced energy. Leading high-mix low-volume production of digitizers for power-plant scale plasma diagnostics, collaborating with fusion scientists to support 70+ instrument interfaces. Designed pointing, acquisition, and tracking system for space-based power beaming including control architecture and actuator/sensor selection. Supporting system design for star trackers (radiometry, link budgets, optomechanics) and spacecraft docking systems (soft capture system). Driving company-wide root-cause analysis training. Developing RAG-based tools to democratize program context.

Founded a 7-person cross-disciplinary R&D team tackling high-novelty, high-uncertainty engineering programs. Led turnaround of ~\$6M in at-risk projects through realignment of technical execution and business goals. Recruited multiple senior technical and people leaders.

Mechanical Engineering Manager. Stabilized and matured mechanical discipline during leadership transition. Developed 3-year roadmap, and foundational review processes. Architected SCARA-type robotic arm for autonomous EV fleet charging at scale: mechanism trade studies, actuator/sensor/camera selection, integration and test, and roadmapping. Performed due-diligence on novel electrostatic end effector and developed low profile, ultra-sensitive capacitive sensors for semiconductor clients.

Senior Systems Engineer. Hands-on technical contributor across diverse early-stage programs. Invented novel high bandwidth temperature sensor (patent pending). Developed a museum-quality digital display for interactive and generative art from concept to low volume production. Architected modular powertrain control systems and wavefront correction actuators for a telescope.

### Honeybee Robotics | Exploration Technologies Division in Altadena, CA

Sept. 2017 - Nov. 2021

Lead, Robotic Systems Group. Systems engineer for LAMPS, a Phase A NASA GCD program to design a 10kW vertically deployable solar array for lunar habitation. Led development of KArLE, a TRL6 sample handling system for lunar exploration with NASA GSFC. Invented novel methods for solid-state sample analysis and manipulation for integration into robotic sampling systems for Europa with JPL. Directed knowledge sharing and processes improvement efforts.

Robotics Engineer III / Project Engineer. Led design of pneumatic sampling system for Dragonfly (New Frontiers 4 mission); won NASA mission selection, matured novel architecture from TRL1 to TRL5 in 16mo. Developed piezo-pneumatic drilling approach for CLPS payload LISTER. Led SBIR, PICASSO, SESAME work on cryogenic thermo-mechanical drilling.

## Independent Consulting

The Choreodaemonic Platform (2025). Created 14-DOF robotic puppeteer from scratch working after-hours over 4 weeks. Sole technical contributor to design and build, actuator selection, kinematics, and control software (C++) with real-time setpoint streaming via Open Sound Control. Successfully installed for live performance including projection art and multiple dancers.

Lind Art & Technology (2023-2024). Designed custom connector for 2x BLDC + CAN interface for 20kW electric surfboard, balancing extreme environment requirements with unique need for user serviceability (patent pending). Owned mechanical design of tightly-integrated remote from prototype to DFM/DFA, working with foreign EE, FW, and contract manufacturing.

Alta Motors (2016-2017). Developed robotic fixtures and controllers for assembly of custom, high-energy-density batteries including QA instrumentation and PLM-compatible technician tools for electric motocross bike.

#### Internships

Alta Motors (2016). Developed instrumented mechanisms for battery assembly during production ramp.

SpaceX (2015). Designed and qualified coaxial connectors and supported enclosure architectures for point-to-point avionics.

Columbia University (2013, 2014). Developed high-throughput neuron injury device and flexible cell culture plates.

Max-Planck Institute (2012). Built diagnostic tools and fixtures for plasma wakefield accelerator research.

## Education

University of Pennsylvania | Philadelphia, PA

M.S.E. in Robotics, GRASP Lab, '16

B.S.E. Cum Laude in Mechanical Engineering and Applied Mechanics, '16

#### **Technical Skills**

Software SolidWorks, Inventor, SolidCAM, Altium, COMSOL, Confluence/Jira, github

Actuator types BLDC, BDC, stepper, piezo MLA, solenoid, distributed-mode loudspeakers, paraffin/SMA, pneumatic Sensor types TC/RTD, pressure, encoder, potentiometer, Hall effect, accelerometer/gyroscope, ultrasonic/laser distance,

capacitive/inductive proximity, phototransistor, strain gauge, camera, fluid mass flow

**Programming** Prefer Linux env., Python/MATLAB for prototyping or analysis, C++ for real-time (controllers)

**DFM** GD&T, Machine tools, 3D printing (FDM, SLA, SLS), laser cutting, waterjet, urethane casting, injection molding,

sheet metal, PCB/PCBA, EB welding, harnessing, electroforming, wire-EDM, optical alignment, woodworking

Embedded STM32, RBPi, Particle IoT, Arduino, LabJack, NI-DAQ, Copley, Elmo

Other Customer interfacing, graphical illustration, technical documentation/writing, industrial design



### **Publications**

- Full-text and more available at tighecosta.com/publications
- Solid State Sample Handling with Amplified Piezo Actuators. Costa JT, Ridilla A, Sanasarian L, Zacny K. *Proceedings of the 2022 IEEE Aerospace Conference*, Big Sky, MT. March 2022.
- Survey, Evaluation, and Advancement of Sample Sensing Techniques for Future Missions. Costa JT, Sanasarian L, Sanigepalli V, Lam S, Stolov L, Palmowski J, Kancans R, Tosi LP, Roberts E, Kriechbaum K. *Proceedings of the 2022 IEEE Aerospace Conference*, Big Sky, MT. March 2022.
- Development and Testing of a Sample Handling System for In-Situ Lunar Geochronology with KArLE. Costa JT, Lang CT, Corrigan P, Emery JW, Thompson LA, Jensen NA, Rideout HT, Indyk S, Yen B, Zacny K, Mullin M, Cattani F, Frese E, Stysley P, Cohen BA. *Proceedings of the 2022 IEEE Aerospace Conference*, Big Sky, MT. March 2022.
- Dragonfly Mass Spectrometer Boldly Goes Where No Other Ion Trap Mass Spectrometer Has Gone Before: Saturn's Moon Titan. Grubisic A, Trainer M, Brinckerhoff W, Van Amerom F, Li X, Danell R, Kaplan D, Malespin C, Costa JT, Rehnmark F, Zacny K, Lorenz R, Barnes J, Turtle E. *Proceedings of the 2020 ASMS Conference on Mass Spectrometry and Allied Topics*, June 2020.
- Development and Testing of a Sample Cup for Laser-Based Instruments. Costa JT, Grubisic A, Sparta J, Li X, Castillo M, Holmes V, Crandall C, Yen B, Rehnmark F, Trainer M, Lorenz R, Zacny K. *Proceedings of the 2019 Astrobiology Science Conference (AbSciCon)*, June 2019.
- SLUSH: Search for Life Using Submersible Heated Drill. Zacny K, Hand K, Sotin C, Howell S, Cwik T, Mueller J, Ehlmann B, Nagihara S, Tipton M, Liller S, Rehnmark F, Costa JT, Bergman D, Hovik W. *Proceedings of the 2019 Astrobiology Science Conference (AbSciCon)*, June 2019.
- Sampling the Ocean Worlds: Drilling and Pneumatic Transfer. Sparta J, Costa JT, Sanigepalli V, Yu D, Ng P, Bailey J, Yen B, Rehnmark F, Zacny K, Lorenz R. *Proceedings of the 2019 Astrobiology Science Conference (AbSciCon)*, June 2019.
- Application of Pneumatics in Delivering Samples to Instruments on Planetary Missions. Zacny K, Lorenz R, Rehnmark F, Costa JT, Sparta J, Sanigepalli V, Yen B, Yu D, Bailey J, Bergman D, Hovik W. *Proceedings of the 2019 IEEE Aerospace Conference*, March 2019.
- SLUSH: Search for Life Using Submersible Heated Drill. Zacny K, Costa JT, Rehnmark F, Mueller J, Cwik T, Zimmerman W, Chow P. Proceedings of the 49th Lunar and Planetary Science Conference, August 2018. #2083
- Drilling Into Titan Cryogenic Materials: Water-Ammonia Ice and Paraffin Wax. Sparta J, Lorenz R, Costa JT, Rehnmark F, Zacny K. Proceedings of the 49th Lunar and Planetary Science Conference, August 2018. #3008
- Cryogenic Sample Acquisition and Delivery System (CryoSADS) for Titan and Europa. Zacny K, Lorenz R, Rehnmark F, Costa JT, Bailey J, Traeden N, Mank Z, Sparta J. *Proceedings of the 42nd COSPAR Scientific Assembly*, July 2018.
- Pneumatic Sample Acquisition and Transfer for 'Ocean Worlds' Landers. Lorenz R, Zacny K, Costa JT, Rehnmark F, Sparta J, Traeden N, Mank Z. *Proceedings of the 15th International Planetary Probe Workshop (IPPW)*, June 2018.
- Surface and Subsurface Sampling Drills for Life Detection on Ocean Worlds. Rehnmark F, Zacny K, Costa JT, Mank Z, Bailey J, Sparta J, Chow P, Traeden N. *Proceedings of the 15th International Planetary Probe Workshop (IPPW)*, June 2018.
- Pneumatic Sample Transport for Ocean Worlds. Sparta J, Zacny K, Lorenz R, Rehnmark F, Costa JT, Mank Z, Bailey J, Traeden N. *Proceedings of the 15th International Planetary Probe Workshop (IPPW)*, June 2018.
- **SLUSH: Europa Hybrid Deep Drill.** Zacny K, Mueller J, **Costa JT**, Zimmerman W, Gray A, Cwik T, Chow P, Rehnmark F, Adams G. *Proceedings of the 2018 IEEE Aerospace Conference*, June 2018. DOI: 10.1109/AERO.2018.8396596
- Designing for Uniform Mobility Using Holonomicity. Costa JT, Mark Y. Proceedings of the 2017 IEEE International Conference of Robotics and Automation (ICRA), June 2017. DOI: 10.1109/ICRA.2017.7989285
- Stretch Injury of Human Induced Pluripotent Stem Cell Derived Neurons in a 96 Well Format. Sherman SA, Phillips JK, Costa JT, Cho FS, Oungoulian SR, Finan JD. Scientific Reports, September 2016. DOI: 10.1038/srep34097